

<b>Computational Fluid Dynamics</b>					
<b>Module-No./Abbreviation</b>	<b>Credits</b>	<b>Workload</b>	<b>Term</b>	<b>Frequency</b>	<b>Duration</b>
CE-WP05/CFD	6 CP	180 h	2 <sup>nd</sup> Sem.	Summer term	1 Semester
<b>Courses</b> Computational Fluid Dynamics			<b>Contact hours</b> 4 SWS (60 h)	<b>Self-Study</b> 120 h	<b>Group Size:</b> No Restrictions
<b>Prerequisites</b> Basic knowledge of: partial differential equations and their variational formulation, finite element methods, numerical methods for the solution of large linear and non-linear systems of equations					
<b>Learning goals / Competences</b> Students should become familiar with modern methods for the numerical solution of complicated flow problems. This includes: finite element and finite volume discretizations, a priori and a posteriori error analysis, adaptivity, advanced solution methods of the discrete problems including particular multigrid techniques. After successfully completing the module, the students shall <ul style="list-style-type: none"> <li>• be familiar with the various equations describing fluid dynamics, in particular the Stokes equation, the compressible and incompressible Navier-Stokes equations and Euler, equations, as well as their scope and applicability,</li> <li>• be able to select stable finite element discretizations for each type of equations and know its advantages, disadvantages, limitations and practical realization,</li> <li>• know the convergence properties of the various methods and be able to describe when these convergence rates can be expected in practice,</li> <li>• be able to formulate a posteriori error estimators and know how to use them to improve the efficiency of finite element methods.</li> </ul>					
<b>Content</b> <ul style="list-style-type: none"> <li>• 1) Modelization Velocity, Lagrangian / Eulerian representation; transport theorem, Cauchy theorem; conservation of mass, momentum and energy; compressible Navier-Stokes / Euler equations; nonstationary incompressible Navier-Stokes equations; stationary incompressible Navier-Stokes equations; Stokes equations; boundary conditions</li> <li>• 2) Notations and auxiliary results Differential operators; Sobolev spaces and their norms; properties of Sobolev spaces; finite element partitions and their properties; finite element spaces; nodal bases</li> <li>• 3) FE discretization of the Stokes equations, 1st attempt Stokes equations; variational formulation in <math>\{\text{div } \mathbf{u} = 0\}</math>; non-existence of low-order finite element spaces in <math>\{\text{div } \mathbf{u} = 0\}</math>; remedies</li> <li>• 4) Mixed finite element discretization of the Stokes equations Mixed variational formulation; general structure of finite element approximation; an example of an unstable low-order element; inf-sup condition; motivation via linear systems; catalogue of stable elements; error estimates; structure of discrete problem</li> <li>• 5) Petrov-Galerkin stabilization Idea: consistent penalty term; general structure; catalogue of stabilizations; connection with bubble elements; structure of discrete problem; error estimates; choice of stabilization parameter</li> </ul>					

<ul style="list-style-type: none"> <li>• 6) Non-conforming methods Idea; most important example; error estimates; local solenoidal bases</li> <li>• 7) Streamline formulation Stream function; connection to bi-Laplacian; FE discretizations</li> <li>• 8) Numerical solution of the discrete problems General structure and difficulty; Uzawa algorithm; improved version of Uzawa algorithm; multigrid; conjugate gradient variants</li> <li>• 9) Adaptivity Aim of a posteriori error estimation and adaptivity; residual estimator; local Stokes problems; choice of refinement zones; refinement rules</li> <li>• 10) FE discretization of the stationary incompressible Navier-Stokes equations variational problem; finite elements discretization; error estimates; streamline-diffusion stabilization; upwinding</li> <li>• 11) Solution of the algebraic equations Newton iteration and its relatives; path tracking; non-linear Galerkin methods; multigrid</li> <li>• 12) Adaptivity Error estimators; type of estimates; implementation</li> <li>• 13) Finite element discretization of the instationary incompressible Navier-Stokes equations Variational problem; time-discretization; space discretization; numerical solution; projection schemes; characteristics; adaptivity</li> <li>• 14) Space-time adaptivity Overview; residual a posteriori error estimator; time adaptivity; space adaptivity</li> <li>• 15) Discretization of compressible and inviscid problems Systems in divergence form; finite volume schemes; construction of the partitions; relation to finite element methods; construction of numerical fluxes</li> </ul>
<p><b>Teaching methods / Language</b> Lecture (2h / week), Exercises (2h / week) / English</p>
<p><b>Mode of assessment</b> Written examination (120 min, 100%)</p>
<p><b>Requirement for the award of credit points</b> Passed final module examination</p>
<p><b>Module applicability</b> MSc. Computational Engineering</p>
<p><b>Weight of the mark for the final score</b> 6 %</p>
<p><b>Module coordinator and lecturer(s)</b> Prof. Dr. P. Henning, Assistants</p>
<p><b>Further information</b></p>